



**COMPATIBLE WITH**

- ▶ Remote control weapon systems
- ▶ Camera tracking systems
- ▶ Gimbal systems
- ▶ Radar systems
- ▶ Rotator systems
- ▶ Turret systems
- ▶ Vehicle cabin/body systems
- ▶ Aircraft cabin systems



**FACTS**

- ▶ 6 degrees of freedom
- ▶ 6 electro-mechanical actuators
- ▶ 4.000 kg total payload
- ▶ 600 mm actuator stroke



**APPLICATIONS**

- ▶ Turret & RCW test
- ▶ Component validation
- ▶ Signal replication
- ▶ Signal generation
- ▶ Real time simulation table
- ▶ Field data system testing simulator

3D CONNECTION CONTROLLER  
OPTIONAL



**SMOTION PRODUCT LINE**

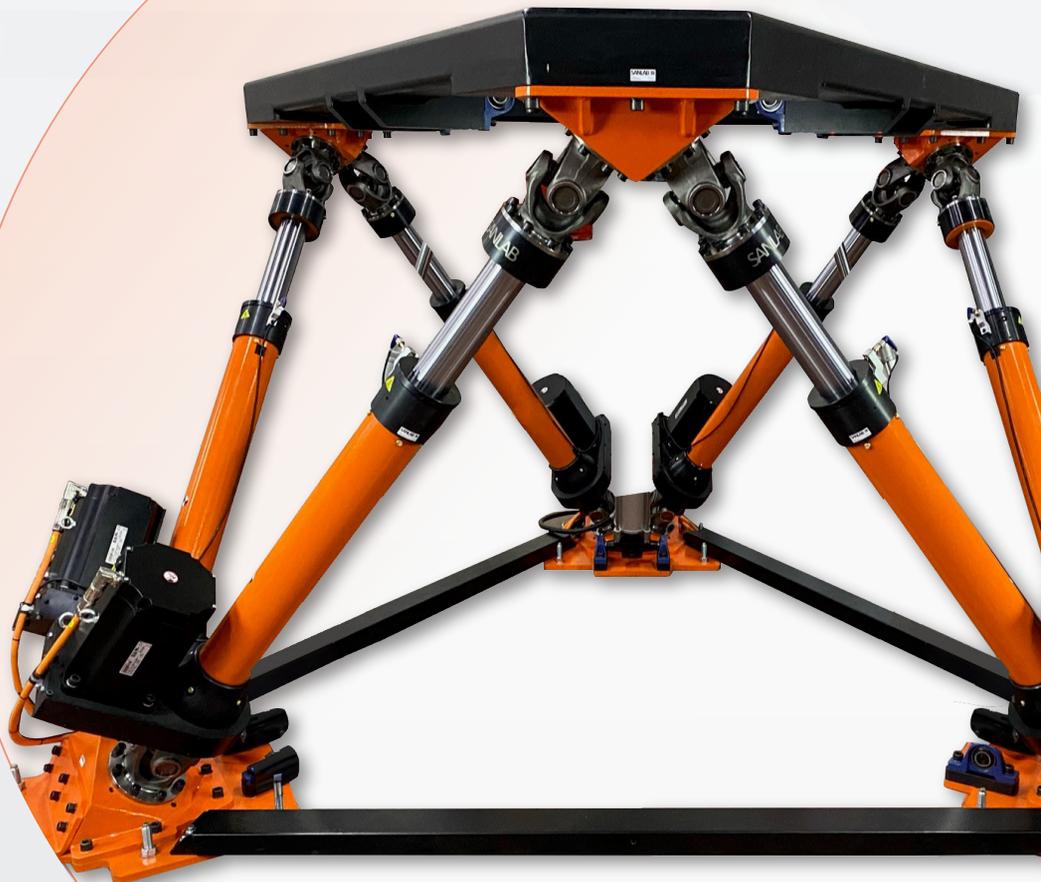
**SMOTION4000**

- SMOTION6000
- SMOTION8000
- SMOTION10000
- SMOTION12000
- SMOTION14000



**DIMENSIONS**

**L2.9Xw3.0XH2.1 m**





**TECHNICAL SPECIFICATIONS**

**Performance Specifications**

- ▶ Gross Moving Load up to **4.000 kg**
- ▶ Actuator Stroke **600 mm**
- ▶ Center of Gravity Above Top Platform **1.00 m (Max)**
- ▶ Settled Height **1.28 m**
- ▶ Neutral Height **1.70 m**

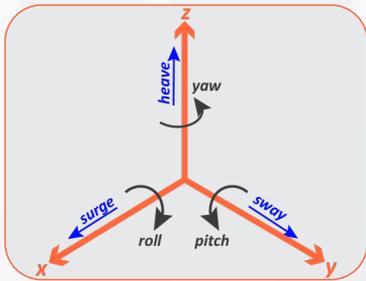
**Moment of Inertia About**

- ▶ Moment of Inertia About X axis **5.650 kg.m<sup>2</sup>**
- ▶ Moment of Inertia About Y axis **5.650 kg.m<sup>2</sup>**
- ▶ Moment of Inertia About Z axis **5.650 kg.m<sup>2</sup>**

**Power Supply**

- ▶ **380VAC ±10%, 3ph , 50/60Hz**

	<b>Velocity</b>	<b>Acceleration</b>
▶ Surge	± <b>0.75 m/s</b>	± <b>7 m/s<sup>2</sup></b>
▶ Sway	± <b>0.75 m/s</b>	± <b>7 m/s<sup>2</sup></b>
▶ Heave	± <b>0.62 m/s</b>	± <b>7 m/s<sup>2</sup></b>
▶ Roll	± <b>40<sup>0</sup>/s</b>	± <b>200<sup>0</sup>/s<sup>2</sup></b>
▶ Pitch	± <b>40<sup>0</sup>/s</b>	± <b>200<sup>0</sup>/s<sup>2</sup></b>
▶ Yaw	± <b>50<sup>0</sup>/s</b>	± <b>300<sup>0</sup>/s<sup>2</sup></b>



**Excursion**

	<b>Single Axis</b>		<b>Multi Axis</b>	
▶ Surge	<b>-0.42 m</b>	<b>0.53 m</b>	<b>-0.58 m</b>	<b>0.57 m</b>
▶ Sway	<b>-0.43 m</b>	<b>0.43 m</b>	<b>-0.62 m</b>	<b>0.62 m</b>
▶ Heave	<b>-0.40 m</b>	<b>0.35 m</b>	<b>-0.40 m</b>	<b>0.35 m</b>
▶ Roll	<b>-20.60<sup>0</sup></b>	<b>20.60<sup>0</sup></b>	<b>-26.41<sup>0</sup></b>	<b>26.41<sup>0</sup></b>
▶ Pitch	<b>-20.20<sup>0</sup></b>	<b>21.20<sup>0</sup></b>	<b>-29.70<sup>0</sup></b>	<b>26.01<sup>0</sup></b>
▶ Yaw	<b>-24.00<sup>0</sup></b>	<b>24.00<sup>0</sup></b>	<b>-26.56<sup>0</sup></b>	<b>26.56<sup>0</sup></b>



**HARDWARE COMPONENTS**

- ▶ User friendly interface control (GUI)
- ▶ Hardware real-time control
- ▶ UDP based PC communication
- ▶ IMU integrated measurement system
- ▶ Passive and active limitations



**SIMPLE, SAFE AND ERGONOMIC SOFTWARE**

- ▶ Signal generations
- ▶ Field data signal replication
- ▶ Real time signal visualization
- ▶ Signal recording and processing



**USER FRIENDLY GUI**

