



FACTS

- ▶ 2 degrees of freedom
- ▶ 10 Hz Frequency in both axes
- ▶ 0.05° accuracy
- ▶ 150 kg payload
- ▶ 300 mm actuator stroke
- ▶ IP Class 66: Water, dust and salt resistant



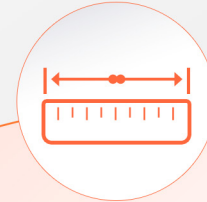
APPLICATIONS

- ▶ IMU integrated stabilization
- ▶ Roll and pitch motion realization
- ▶ Prototype tests
- ▶ Real-time data logging
- ▶ Component validation
- ▶ Vibration isolation



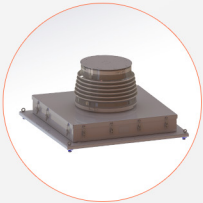
COMPATIBLE WITH

- ▶ Electro-optic systems
- ▶ Remote control weapon systems
- ▶ Radar systems
- ▶ Drones



DIMENSIONS

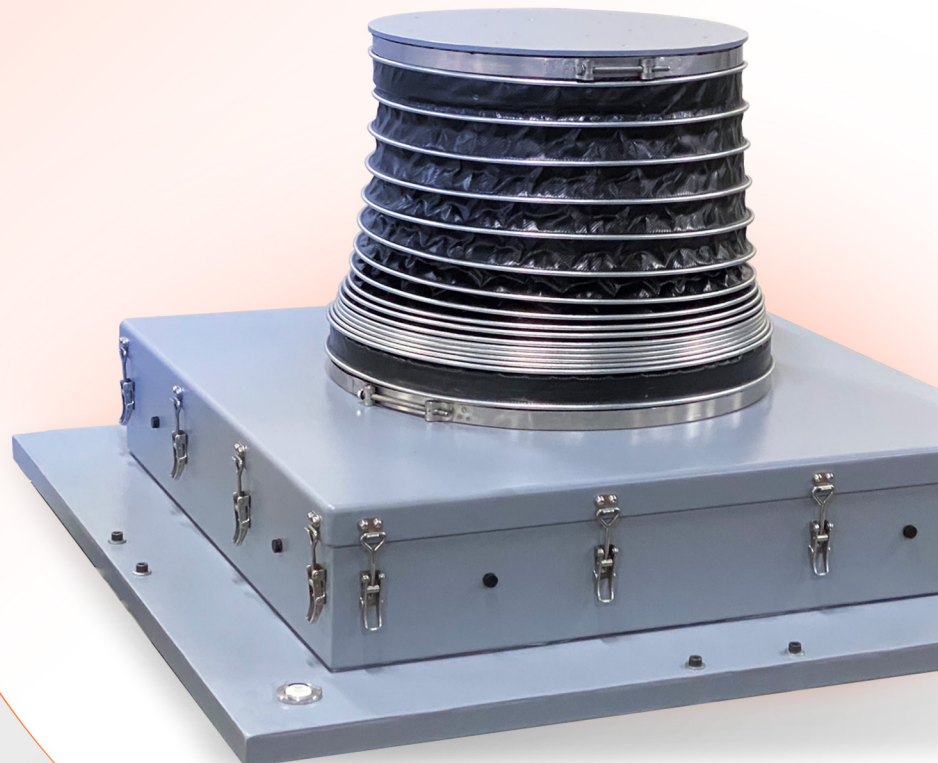
L1.2XW1XH0.8 m



PRODUCT LINE

STABILIZER150

STABILIZER300





TECHNICAL SPECIFICATIONS

Performance Specifications

- ▶ Gross Moving Load up to **150 kg**
- ▶ Actuator Stroke **300 mm**
- ▶ Center of Gravity Above Top Platform **0.5 m (Max)**
- ▶ Mass **220 kg**
- ▶ Footprint **1.2 x 1 x 0.8 m**

- | | Excursion | Velocity | Acceleration |
|---|------------------|-----------------|---------------------|
| ▶ Roll | $\pm 30^0$ | $\pm 50^0/s$ | $\pm 280^0/s^2$ |
| ▶ Pitch | $\pm 30^0$ | $\pm 30^0/s$ | $\pm 280^0/s^2$ |
| Operation Temperature -10 ... +50 | | | |
| Storage Temperature -20 ... +60 | | | |
| Power Supply 400VAC $\pm 10\%$, 3ph , 50/60Hz | | | |

- Moment of Inertia About**
- ▶ Surge **90 kg.m²**
 - ▶ Sway **90 kg.m²**
 - ▶ Heave **90 kg.m²**



HARDWARE COMPONENTS

- ▶ User friendly interface control (GUI)
- ▶ Hardware real-time control
- ▶ UDP based PC communication
- ▶ Joystick control in all axis
- ▶ Passive and active limitations
- ▶ Joystick Control



SOFTWARE CAPABILITY

- ▶ Stabilization control algorithm
- ▶ Disturbance rejection motion control
- ▶ IMU signal recording
- ▶ Real-time monitoring of system variables



USER FRIENDLY GUI

